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FASSTest-2.4GHz Bidirectional Communication System S.BUS2 / S.BUS Port and Conventional System Receiver

# **INSTRUCTION MANUAL**

HV

FASSTest S.BUS S.BUS 2

Applicable systems: Futaba FASSTest-2.4GHz system-

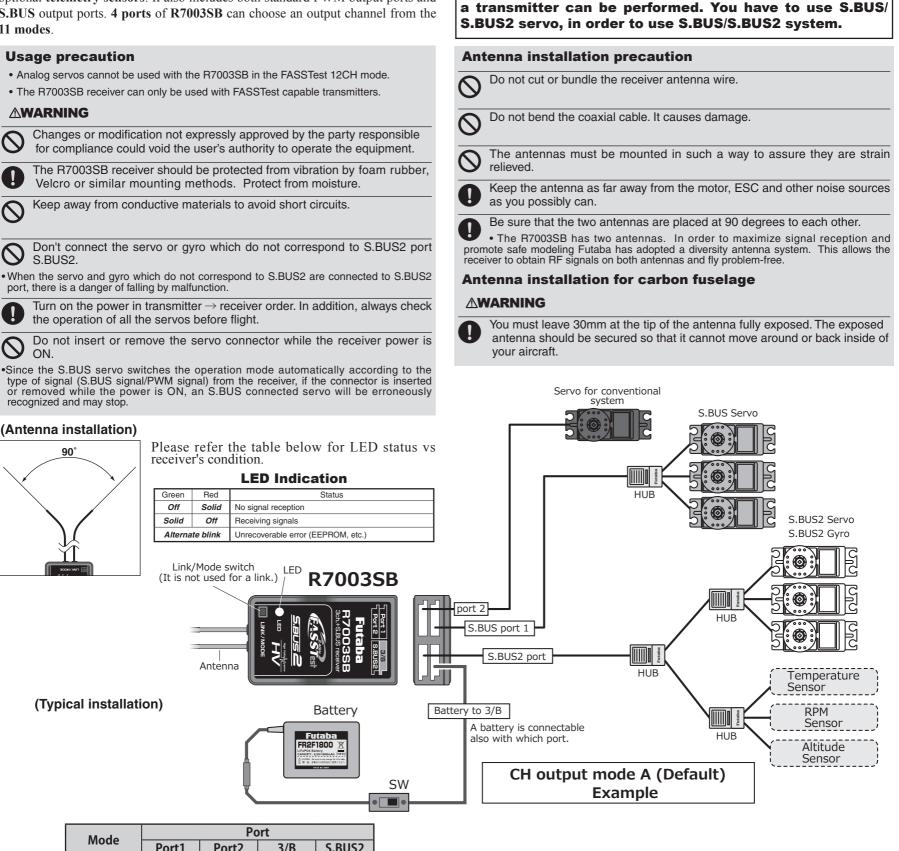
transmitter

If R7003SB does not use S.BUS/S.BUS2 system, it can

perform only operation of 3 channels. However, if S.BUS/

S.BUS2 system is used, use of the maximum channel of

Thank you for purchasing a Futaba R7003SB FASSTest-2.4GHz compatible receiver. The R7003SB receiver features bi-directional communication with a FASSTest Futaba transmitter using the S.BUS2 port. Using the S.BUS2 port an impressive array of telemetry sensors may be utilized. R7003SB has a merit which acquires the information from the model on flight by connecting an optional telemetry sensors. It also includes both standard PWM output ports and S.BUS output ports. 4 ports of R7003SB can choose an output channel from the 11 modes



## **FASSTest**

**FASSTest** is a bidirectional communication system between the R7003SB receiver and FASSTest capable transmitters. Multiple optional telemetry sensors may be connected to the S.BUS2 on the receiver and that data is in turn displayed on the transmitter.

\*Please see your transmitters operation manual to configure transmitter to operate with telemetry sensors.

## **R7003SB Specifications**

- FASSTest-2.4GHz system/S.BUS2 and S.BUS port and conventional system receiver
- Dual antenna diversity
- Size: 0.89 x 1.47 x 0.37 in.(22.5 x 37.4 x 9.3 mm) Weight: 0.25 oz. (7.2g) Power requirement: 3.7V to 7.4V(Voltage range: 3.5 to 8.4V)
- Battery F/S Voltage: It sets up with a transmitter Extra Voltage port (port2)"EXT-VOL cable and CA-RVIN-700" of an option is used: 0  $\sim$  70V DC

\* Be sure that when using ESCs regulated output the capacity of the ESC must meet your usage condition.

of more than 20cm from human body. To meet the RF exposure requirements of the FCC this device shall not be co-located with another transmitting device.

(for U.S.A.)

undesired operation.

The responsible party of this device compliance is:

Futaba Service Center

A(Default)

S.BUS

CH2

This device, trade name Futaba Corporation, model number R7003SB, complies with part15 of the

(2) This device must accept any interference received, including interference that may cause

(3) This module meets the requirements for a mobile device that may be used at separation distances

CH3

S.BUS2

3002 N Apollo Drive Suite 1, Champaign, IL 61822 U.S.A.

**Compliance Information Statement** 

FCC Rules. Operation is subject to the following two conditions (1) This device may not cause harmful interference, and

TEL (217)398-8970 or E-mail: support@futaba-rc.com (Support)

## S.BUS2

S.BUS2 extends S.BUS and supports bidirectional communication. Sensors are connected to the S.BUS2 port.

Port	S.BUS Servo S.BUS Gyro	S.BUS2 Servo S.BUS2 Gyro	Telemetry sensor
S.BUS	0	0	×
S.BUS2	× (*)	0	0

\*Only S.BUS2 capable devices may be connected to the S.BUS2 port. Standard S.BUS servos and gyros should not be connected to the S.BUS2 port.

#### Link to the transmitter

Easy Link ID allows FASSTest receivers to link to compatible transmitter without pressing the link button on the receiver.

1 Bring the transmitter and the receiver close to each other, within 20 inches (half meter).

2 Turn on the transmitter. Place the transmitter into the receiver linking mode.

## **3** Turn on the receiver.

4 When the LED of the receiver changes from blinking red to solid green, linking is complete.

\* Refer to the transmitters operation manual for complete details on how to place the transmitter into the linking mode.

- If there are many FASSTest systems turned on in close proximity, your receiver might have difficulty establishing a link to your transmitter. This is a rare occurrence. However, should another FASSTest transmitter/receiver be linking at the same time, your receiver could link to the wrong transmitter. This is very dangerous if you do not notice this situation. In order to avoid the problem, we strongly recommend you to double check whether your receiver is really under control by your transmitter.
- \* If the System Type of the transmitter is changed, the receiver will need to be re-linked to the transmitter
- \* Link is required when a new model is made from a model selection

#### WARNING

Do not perform the linking procedure while the motor's main wire connected  $\bigcirc$ or the engine is operating as it may result in serious injury.

When the linking is complete, please cycle the receiver power and ensure the receiver is properly linked to the transmitter.

Please power up your system in this order. Transmitter first, followed by the receiver

If the R7003SB receiver was previously linked to another transmitter, make sure that transmitter is not operating while linking the receiver to the new transmitter.

## **Channel Modes**

The R7003SB is capable of changing its channel allocations as described in the table below. Please choose the mode which suited the use in the following procedure from the 11 modes

- Press and hold down the Link/Mode button on the R7003SB receiver. [Transmitter is always OFF] 1
- 2 Turn the receiver on while holding down the Link/Mode button. After power up, the button can be released.
- **3** The LED should now be blinking red with green.
- 4 Each press of the Mode/Link button advances the receiver to the next mode. [Refer to CH Mode table shown below.]
- 5 When you reach the mode that you wish to operate in, press and hold the Mode/Link button for more than 2 seconds.
- 6 When LED blinks in green with red, it is the completion of a mode change.

7 Please cycle the receiver power off and back on again after changing the Channel Mode. \*5 seconds after the receiver ON. LED shows CH Mode

#### R7003SB CH Mode table

Mode	Port			LED blink		
Mode	Port1	Port2	3/B	S.BUS2	LED DIINK	
A(Default)	S.BUS			S.BUS2	Red 1 time	
В	S.BUS2			S.BUS2	Red 2 time	
C	S.BUS	CH2		S.BUS	Red 3 time	
D				S.BUS	Red 4 time	
E	CH1				Green 1 time	
F		CH4	СНЗ		Green 2 time	
G	CH2	CH4			Green 3 time	
Н	CH1	CH5	]	S.BUS2	Green 4 time	
I	CH2	CH7		Red and Green 1 tim		
J	CH4	CH8			Red and Green 2 time	
К	CH11	CH12			Red and Green 3 time	

#### **Measurement of Extra Voltag**

R7003SB can display the voltage of a receiver battery on a transmitter.

Furthermore, the following procedures are required in order to display the voltage of another battery (Drive battery etc.).

1 The optional adapter for CA-RVIN-700 is purchased.

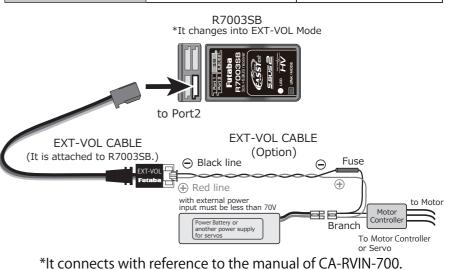
- 2 R7003SB is changed into "EXT-VOL Mode" in the following procedure. \*If "EXT-VOL Mode" is used, the port 2 cannot be used as the servo CH.
- 3 According to the manual of CA-RVIN-700, battery wiring is branched and it connects
- 4 One side of EXT-VOL CABLE is connected to the port 2 of R7003SB.

#### < How to change R7003SB into "EXT-VOL Mode" >

1 Turn on the receiver. LED lights up red. [Transmitter is always OFF]

- 2 Press and hold the Mode/Link button for 5 seconds to 10 seconds.
- \*It becomes the mode which makes a mistake in exceeding 10 seconds. In that case, carry out power supply OFF and redo.
- **3** The LED should now be early blinking green. Mode/Link button is released.
- 4 Each press of the Mode/Link button advances the receiver to the next mode.
- 5 When you reach the mode that you wish to operate in, press and hold the Mode/ Link button for more than 2 seconds.
- 6 When LED blinks in green with red, it is the completion of a mode change.
- 7 Please cycle the receiver power off and back on again after changing the EXT-VOL Mode.

Mode	External voltage measurement	LED blink
Servo Mode(Default)	OFF	Green 1 time
EXT-VOL Mode	ON	Green 2 time



	VARNING
$\overline{\mathbf{O}}$	Don't touch wiring.
C	* There is a danger of receiving an electric shock.
$\overline{\bigcirc}$	Don't connect to Extra Voltage before turning on a receiver.
0	When not using EXT-VOL, "EXT-VOL Mode" is turned OFF.
0	Don't connect EXT-VOL CABLE other than port 2 of R7003SB.

## When using the R7003SB Receiver with the GYA440, GYA441 and CGY750

The following table corresponds to the gyro's functions. A port can be used effectively. The servo which a gyro controls is connected to a gyro. Please refer to the description of each gyro manual.

S.BUS	Gyro	Goup	table
$\mathbf{D}$	0,10	OUup	uuuu

Gyro control CH	CH Mode
Rudder	D,E
Elevator	F
Aileron	G
Elevator+Rudder	Н
Aileron+Rudder	I
Aileron+Elevator	J
Aileron+Elevator+Rudder or CGY750	A

## [Example: Connecting GYA441 to R7003SB CH Mode G]

